



iND60

Double Encoder, No Brake, Integrated Drive

Product number: 1L057X055NBXID

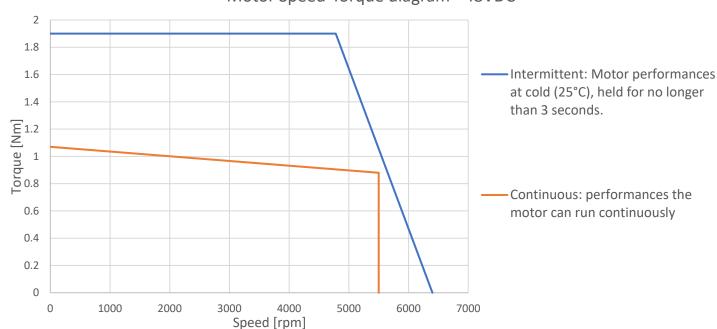


MOTOR SPECIFICATIONS

Characteristic	Abbr.	Unit	Value
Motor technology			SPM
No of poles			10
Rated Voltage	U _{mot}	V _{rms}	48
S1 Rated speed	n _n	rpm	5500
Maximum speed	n _{max}	rpm	6400
Rated power	P _n	W	507
Stall torque	M ₀	Nm	1.07
S1 Rated torque	M _n	Nm	0.88
Peak torque	M _{max}	Nm	1.9
Stall current	I ₀	A _{rms}	17
S1 Rated current	In	A _{rms}	15
Peak current	I _{max}	A _{rms}	27

Characteristic	Abbr.	Unit	Value
Torque constant (hot)	kt _{hot}	Nm/A _{rms}	0.059
Torque constant (cold)	kt _{cold}	Nm/A _{rms}	0.070
Voltage constant	ke	V/krpm	4.9
Winding resistance	R _{p-p}	Ω	0.21
Winding inductance	L _{p-p}	mH	0.33
Max ambient operating			40°C
temperature			
Insulation class			F – 155°C
Thermal Protection			KTY-84

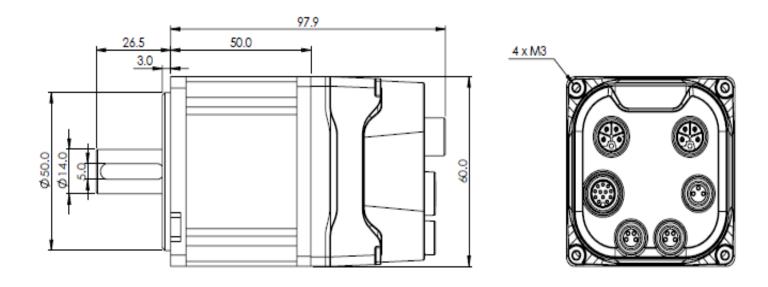
Motor Speed-Torque diagram - 48VDC







MOTOR DIMENSIONS



INTEGRATED DRIVE

Model: Integro

Drive Technical Specifications: https://www.synapticon.com/en/products/somanet-integro

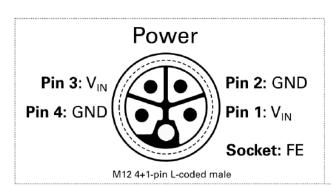
FEEDBACK SPECIFICATIONS

Characteristic	Value
Manufacturer	Renishaw RLS
Туре	Double incremental encoder with Commutation signals
Resolution	12 bit; 4096 ppr
Hysteresis	0.18°
Accuracy	±0.5°
Supply voltage	5 V _{DC}
Current Consumption	13 mA to 50 mA



CONNECTOR GUIDE





STO/SBC

Pin 1: B (+24V)

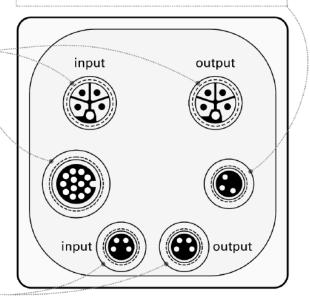
Pin 4: GND

Pin 3: A (+24V)

M8 3-pin A-coded female



Pin 4: Tx-Pin 3: Rx-Pin 1: Tx+



NOTE: 1) The data provided in this datasheet is for guidance only and does not form part of any contract. 2) Motor, drive, gearbox and brake should undergo application testing to validate performance.

iN Motion is part of iNetic $\underline{www.inetic.com}$

info@ineticmotion.com

