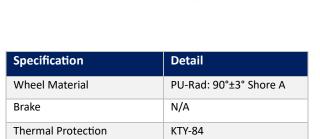




iMR 100

Double encoder, No Brake

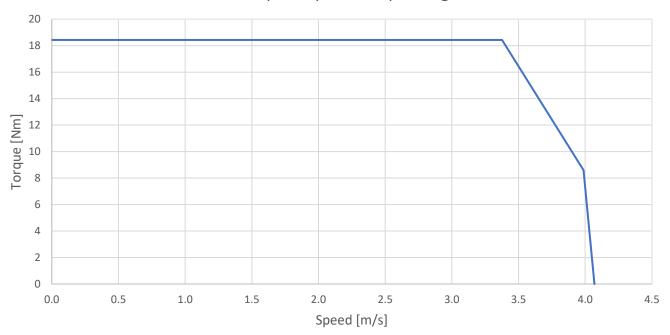
Order number: 1L057X055NXXXD-RT01



Characteristic	Unit	Value
Wheel Diameter	mm	135
Gearbox Type		Planetary Helical
Gearbox Ratio		10:1
Rated Voltage	V _{DC}	48
Max Torque	Nm	18.4
Max Speed	Rpm	576
	m/s	4.07
	km/h	14.6
Peak Power	W	920
Max Radial Load per Wheel	kg	1000
Unit Weight	kg	5

Solution Peak Performance Diagram Output at the Wheel

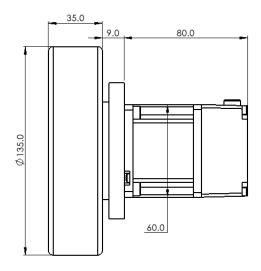
Wheel Output - Speed-Torque Diagram

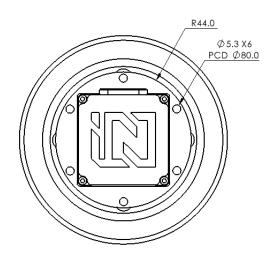






Dimensions



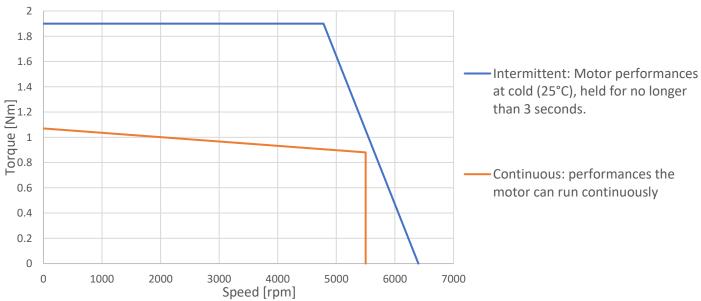


Motor specs

Characteristic	Abbr.	Unit	Value
Motor technology			SPM
No of poles			10
Rated Voltage	U _{mot}	V_{rms}	48
S1 Rated speed	n _n	rpm	5500
Maximum speed	n _{max}	rpm	6400
Rated power	Pn	W	507
Stall torque	M ₀	Nm	1.07
S1 Rated torque	M _n	Nm	0.88
Peak torque	M _{max}	Nm	1.9
Stall current	I ₀	A _{rms}	17
S1 Rated current	In	A _{rms}	15
Peak current	I _{max}	A _{rms}	27

Characteristic	Abbr.	Unit	Value
Torque constant (hot)	kt _{hot}	Nm/A _{rms}	0.059
Torque constant (cold)	kt _{cold}	Nm/A _{rms}	0.070
Voltage constant	ke	V/krpm	4.9
Winding resistance	R _{p-p}	Ω	0.21
Winding inductance	L _{p-p}	mH	0.33
Max ambient operating			40°C
temperature			
Insulation class			F – 155°C

Motor Speed-Torque diagram - 48VDC







Feedback specifications

Characteristic	Value
Manufacturer	Renishaw RLS
Туре	Double incremental encoder with Commutation signals
Resolution	12 bit; 4096 ppr
Hysteresis	0.18°
Accuracy	±0.5°
Supply voltage	5 V _{DC}
Current Consumption	13 mA to 50 mA

Connector guide

No connectors, Cable leads only

Power:

Phase	Cable
U	Black, AWG14
V	Blue, AWG14
W	White, AWG14

Cable length: 0.5 m

Thermistor:

Black and white AWG26 cables

Signal - Feedback 1

Signal	Colour
U	Black
V	Violet
W	Grey/Pink
A+	Pink
A-	Grey
B+	Green
B-	Yellow
Z+	White
Z-	Brown
V _{dd} (+5 V)	Red
GND	Blue

Cable length: 0.3 m

Signal - Feedback 2

Signal	Colour
A+	Pink
A-	Grey
B+	Green
B-	Yellow
Z+	White
Z-	Brown
V _{dd} (+5 V)	Red
GND	Blue

NOTE: 1) The data provided in this datasheet is for guidance only and does not form part of any contract. 2) Motor, drive, gearbox and brake should undergo application testing to validate performance.

iN Motion is part of iNetic $\underline{www.inetic.com}$

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